

LiTell: Robust Indoor Localization Using Unmodified Light Fixtures

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MobiCom'16



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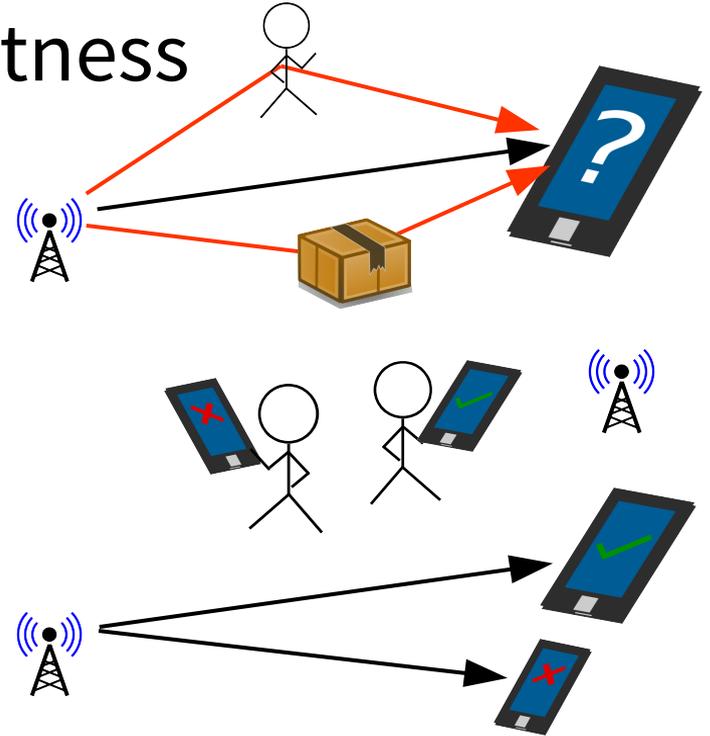
Indoor Localization: Enabling Technology



RF-based Localization

Multiple factors compromise robustness

- Multipath propagation
- Environmental dynamics
- Device heterogeneity



Visible Light Localization

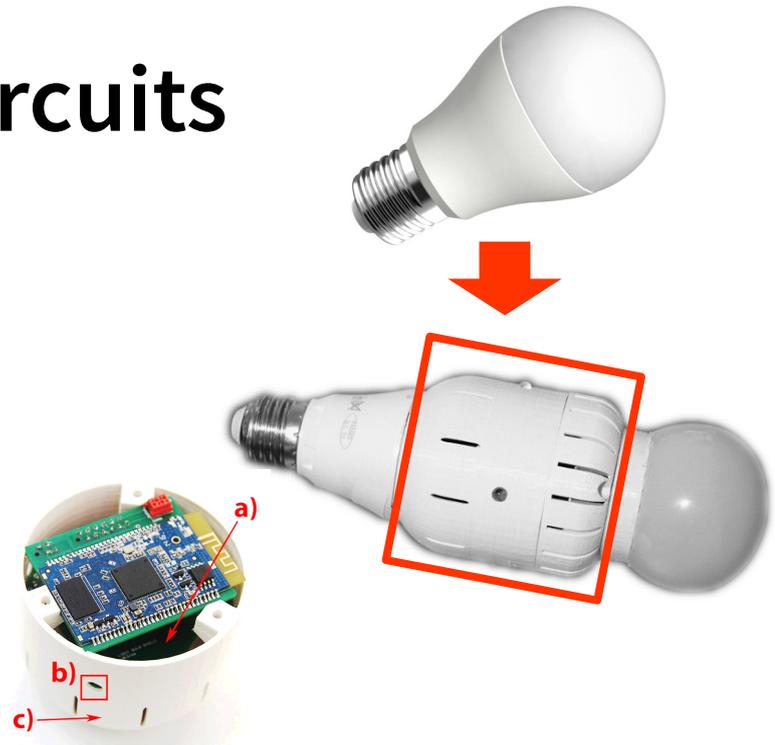
- LoS propagation: **robust, multipath-free**
- Densely deployed landmarks: **high accuracy**
Existing works show **10cm** to **1m** accuracy¹



[1] Y.-S. Kuo, et al., "Luxapose", MobiCom'14; L. Li, et al, "Epsilon", NSDI'14

Deployment Challenges

LED beacons needs **extra circuits**
Adds to **manufacturing cost**

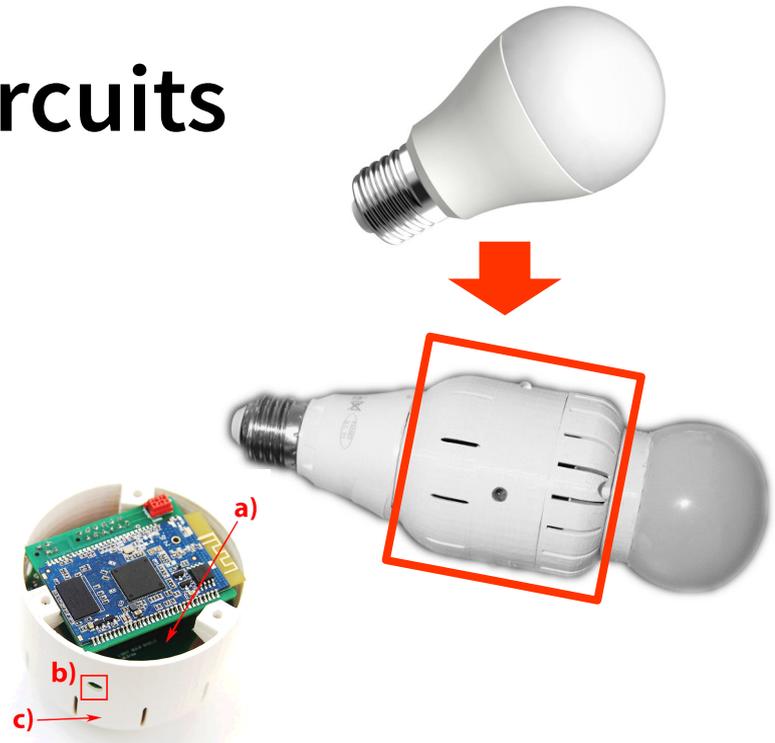


Deployment Challenges

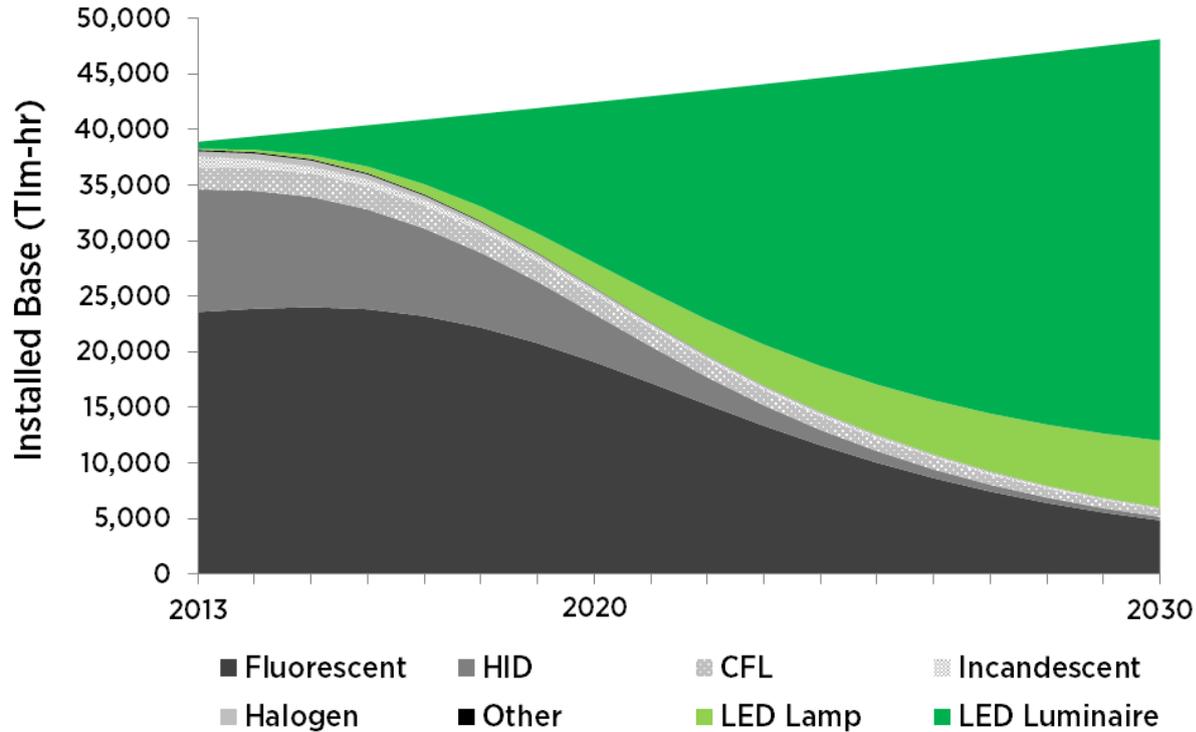
LED beacons needs **extra circuits**

Adds to **manufacturing cost**

Huge **retrofitting effort**



Deployment Challenges



Source:
US DoE

LiTell

- Landmark: **unmodified fluorescent light fixtures**
- Sensor: **smartphone cameras**
- **Zero** retrofitting cost!



Localization Using Incumbent Lights

Fluorescent light driver operates at **high frequency**

This frequency is reflected in the **light emission**

It is **unique** due to manufacturing variations,
hence we call it “**characteristic frequency**” (CF)

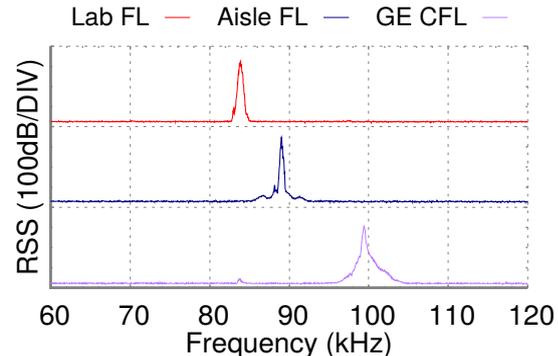
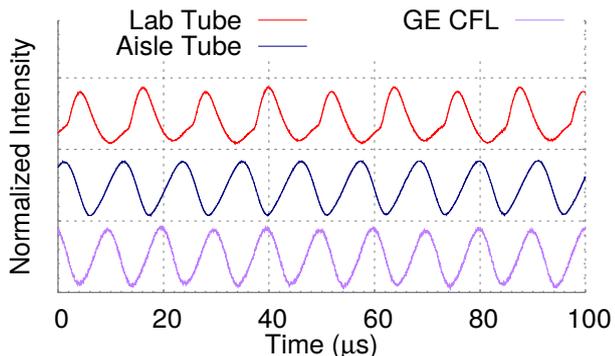
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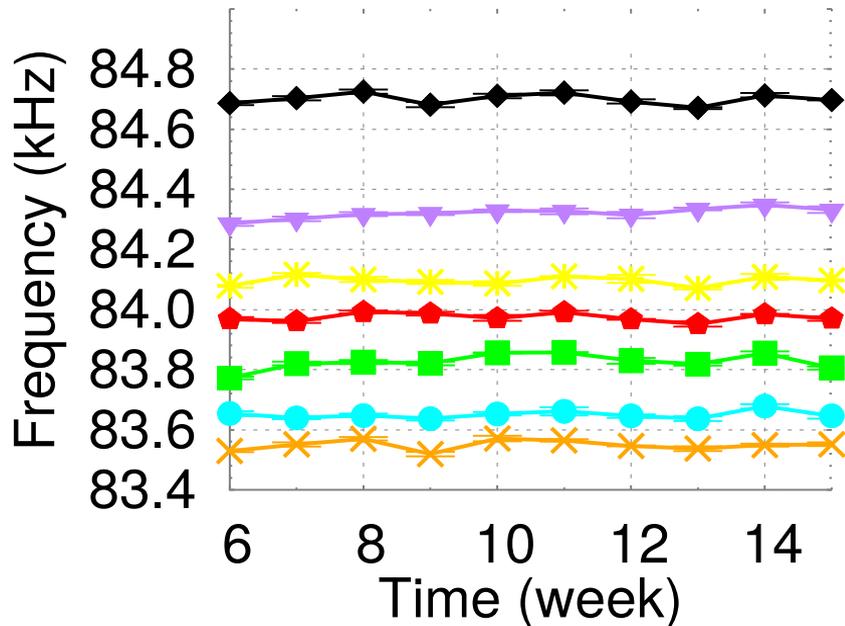
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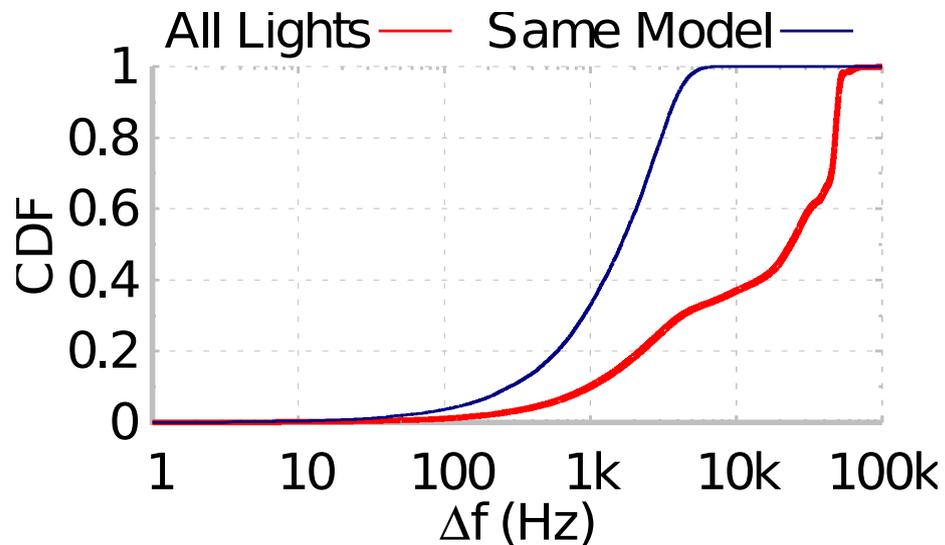


Characteristic Frequency (CF)

7 lights in our lab

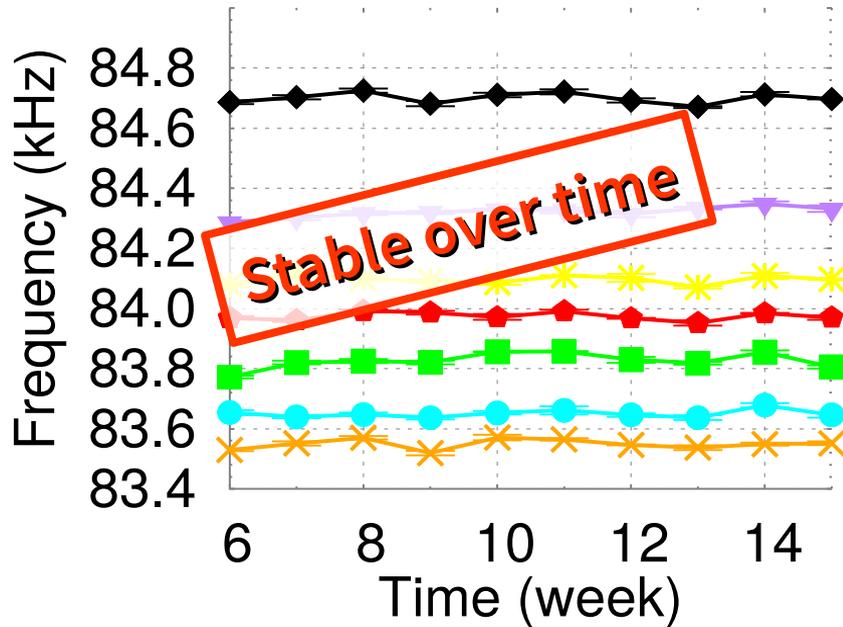


500 lights in an office building

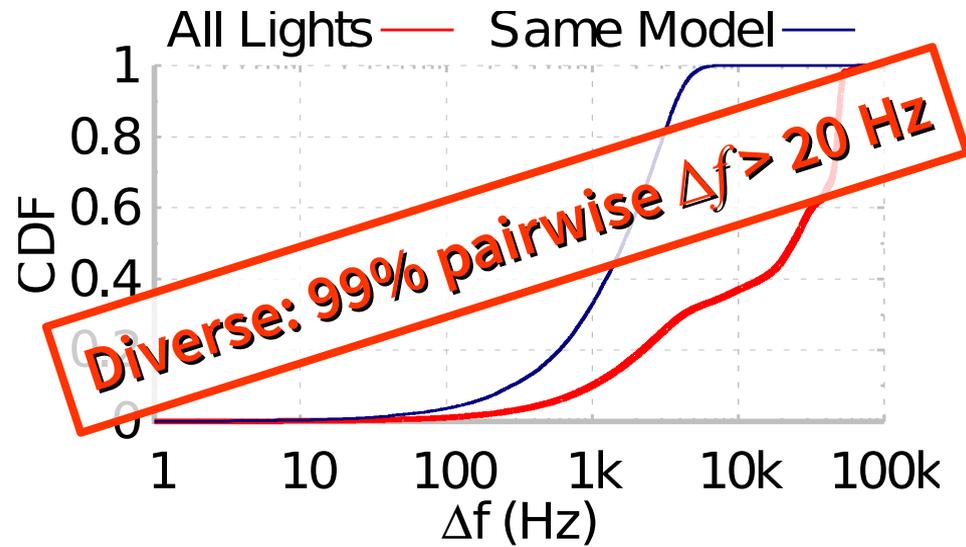


Characteristic Frequency (CF)

7 lights in our lab



500 lights in an office building



Capturing CF on Phones

COTS phones do not have **high speed light sensors**.

Instead, we can use **cameras**.

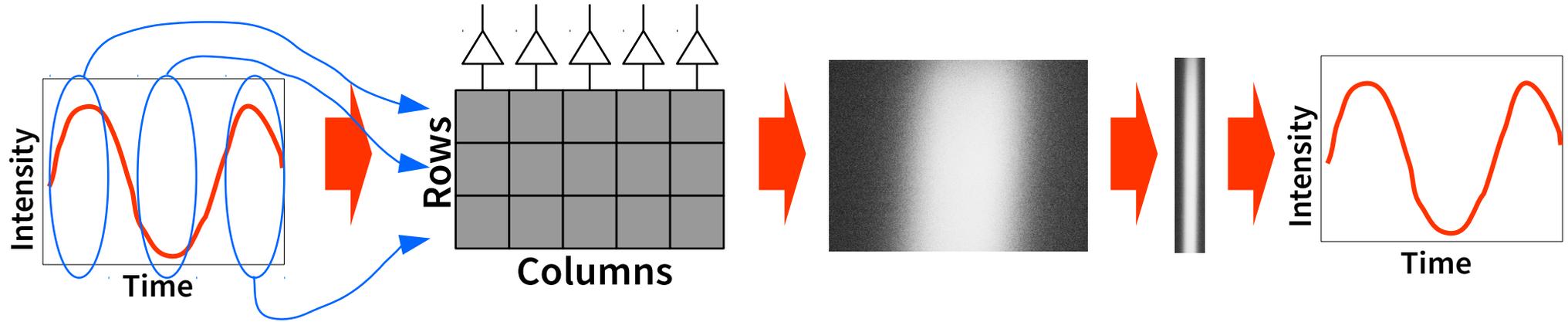
Key Challenges:

- **Low sampling rate**
- **Low SNR**



Sampling CF

Rolling shutter: a primer

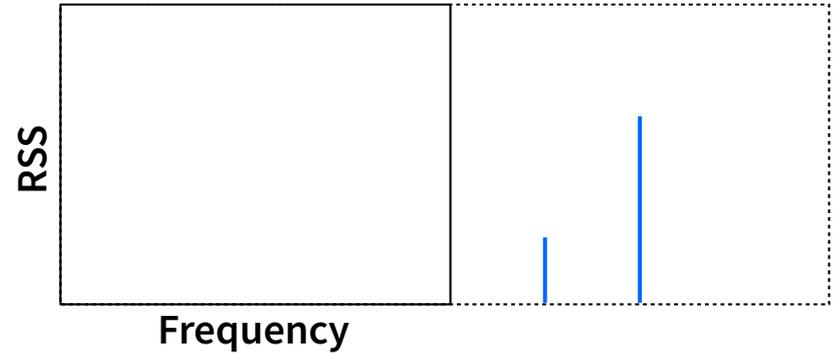


Key benefits: higher sampling rate, reliable timing

Sampling CF

Typical smartphone has sampling rate of **56 ~ 105 kHz**

CFs are around **80 ~ 100 kHz**, need Nyquist sampling rate **> 200 kHz**



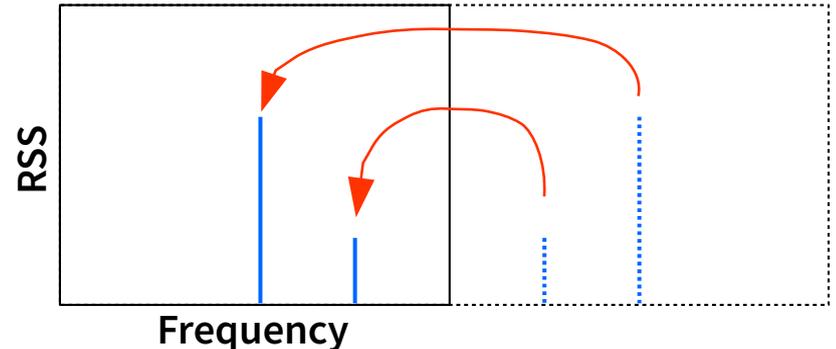
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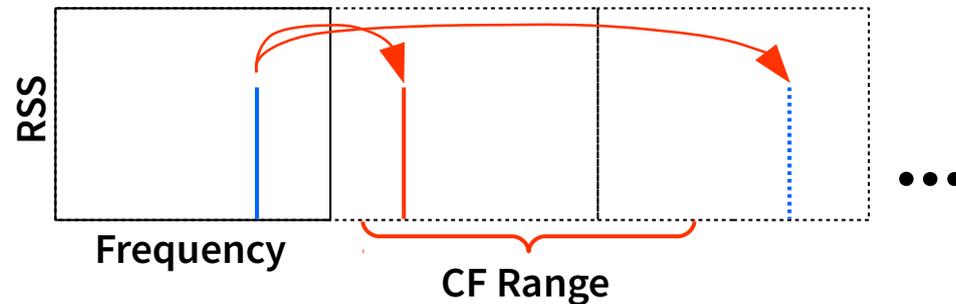
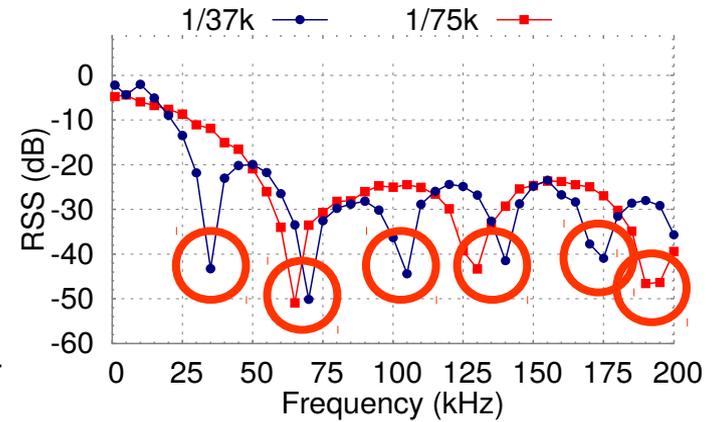
Observation: **CF is extremely sparse**

Solution: **leverage aliasing effect**
(If the analog bandwidth suffices!)



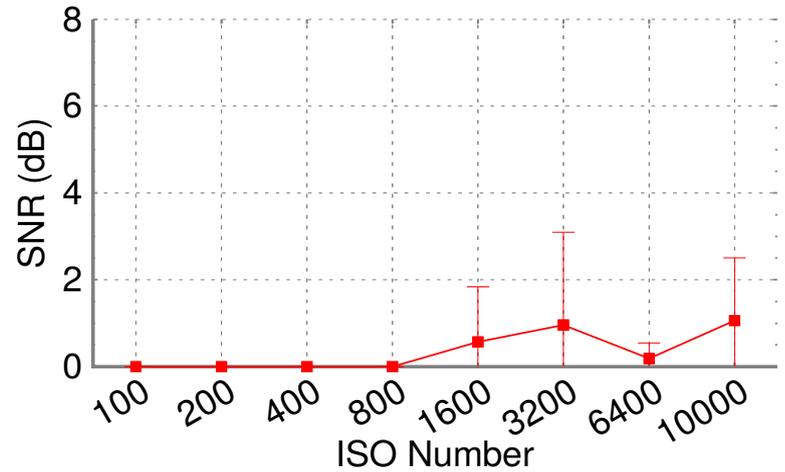
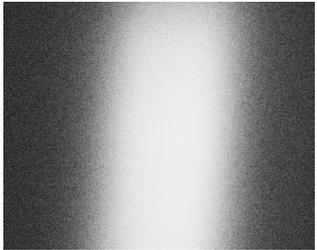
Sampling CF

- Camera's analog bandwidth: up to **200 kHz**
- **Adaptive exposure** to avoid notches
- **De-aliasing** mechanism to disambiguate CF



Boosting SNR

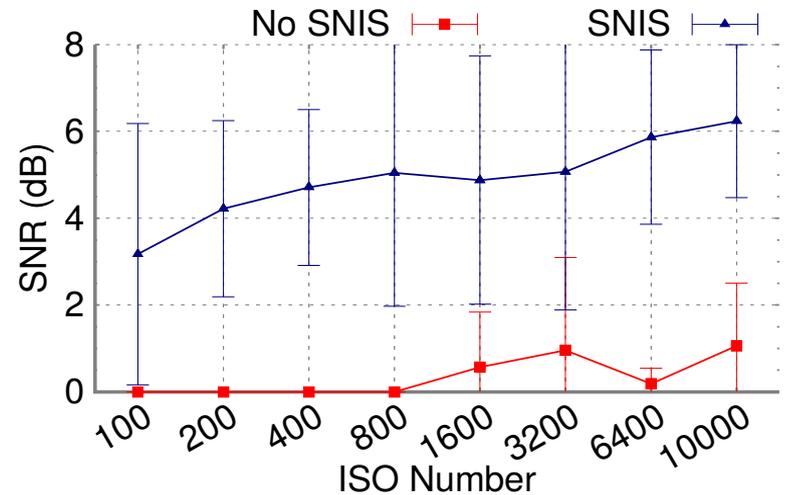
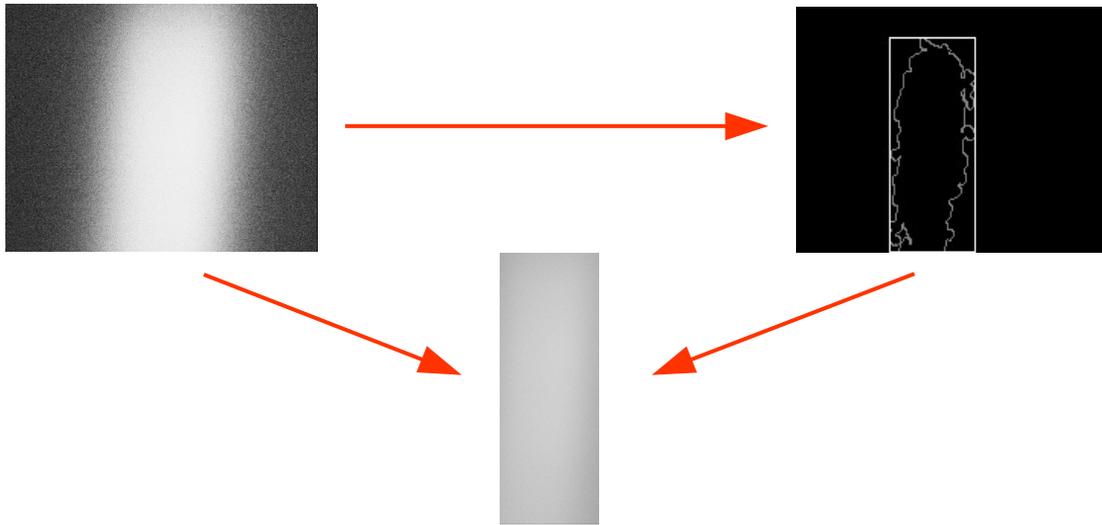
Noise from **dark areas** / **ambient sunlight** reduces SNR.



Boosting SNR

Noise from **dark areas** / **ambient light** reduces SNR.

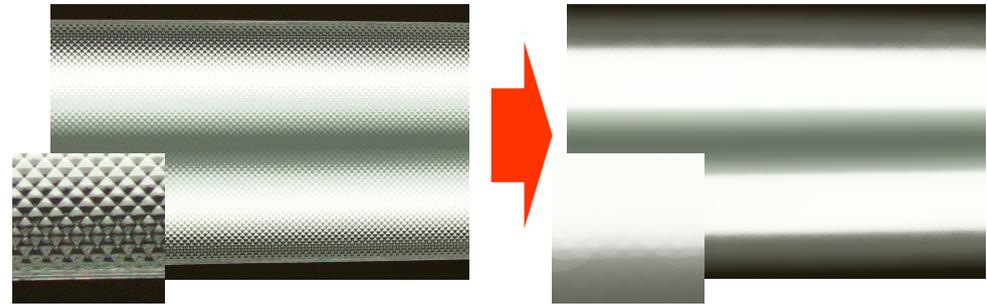
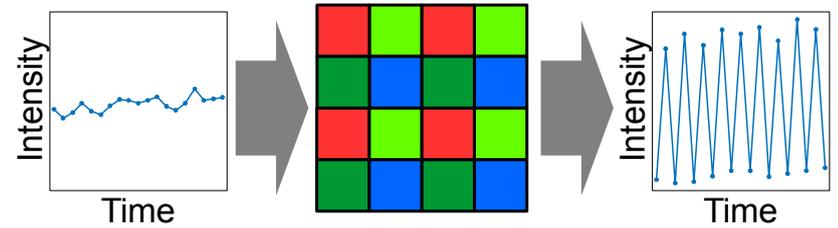
SNIS: fast spatial noise removal tailored for lights



Boosting SNR

Artifacts:

- **Interleaving:** from camera
- **Spatial patterns:** from light cover

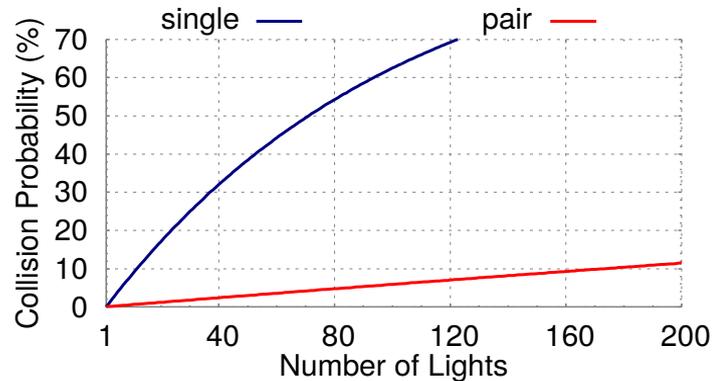


Localization

Identifying individual lights:

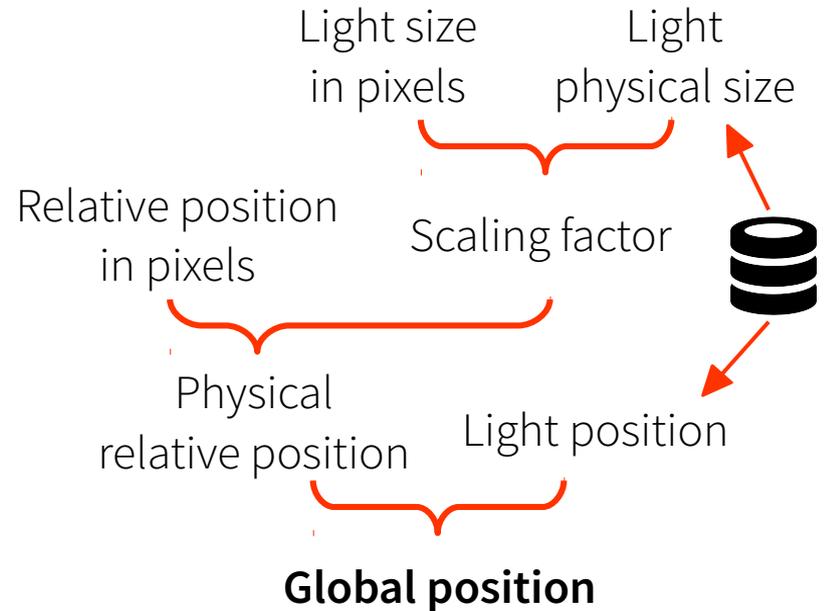
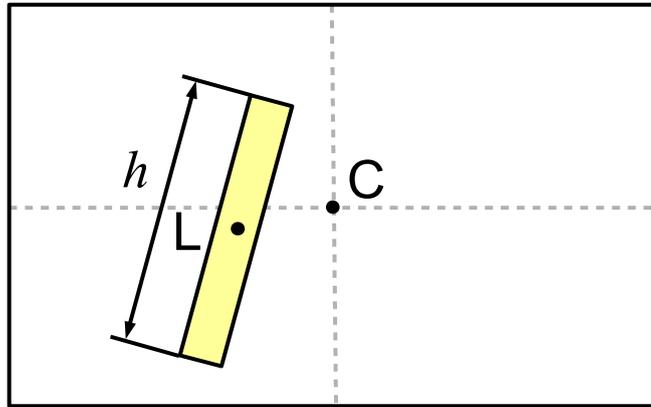
collision rate grows as more lights are added in database

Error control mechanism: **using pairs of consecutive lights**



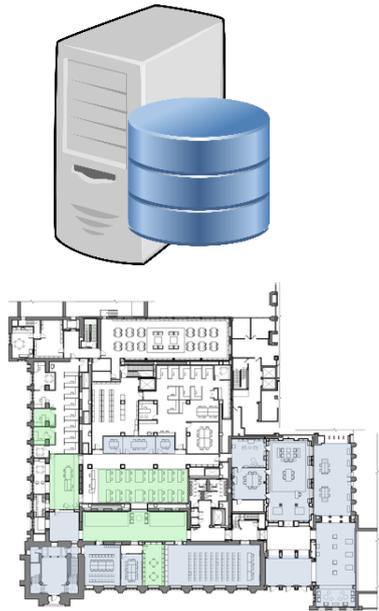
Localization with Respect to a Specific Light

Observation: **images are scaled from physical structure**



Implementation

LiTell Server

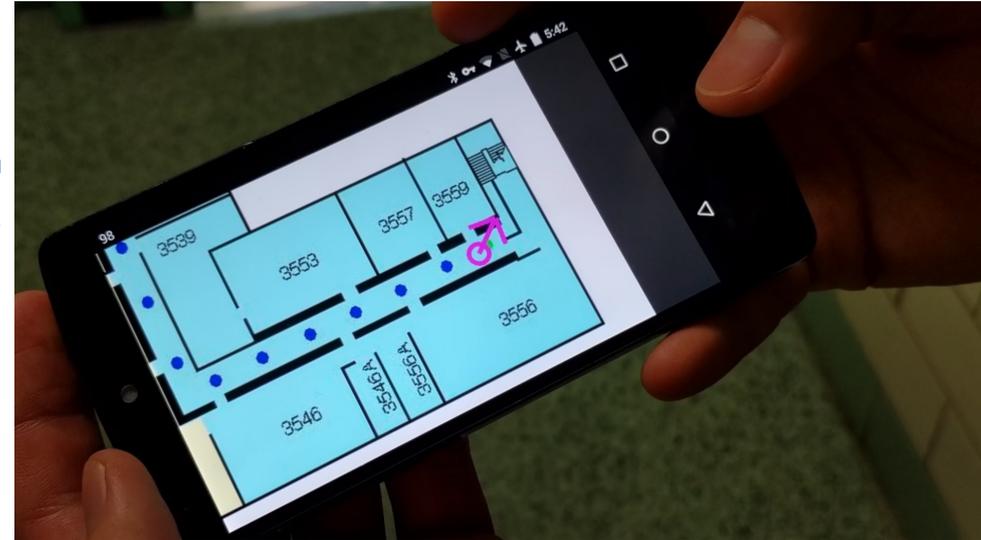


Send ceiling
light samples



Return current
location

LiTell Android App



Experimental Evaluation

- **Robustness**
- **Accuracy**
- **User study**



Robustness

Distance: up to 2m with typical smartphone camera



Robustness

Distance: up to 2m with typical smartphone camera

Ambient light: works by the window with direct sun light



Robustness

Distance: up to 2m with typical smartphone camera

Ambient light: works by the window with direct sun light

User behavior: unaffected by normal pose and walking



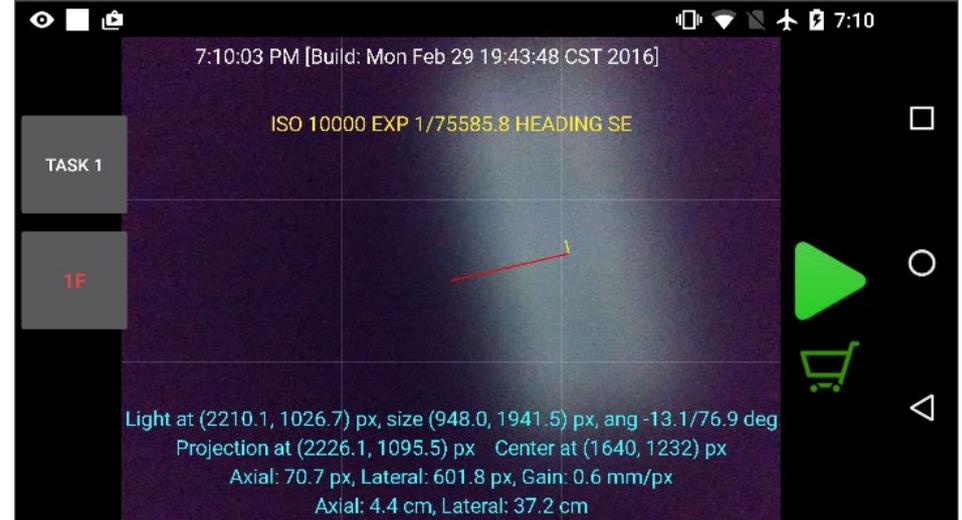
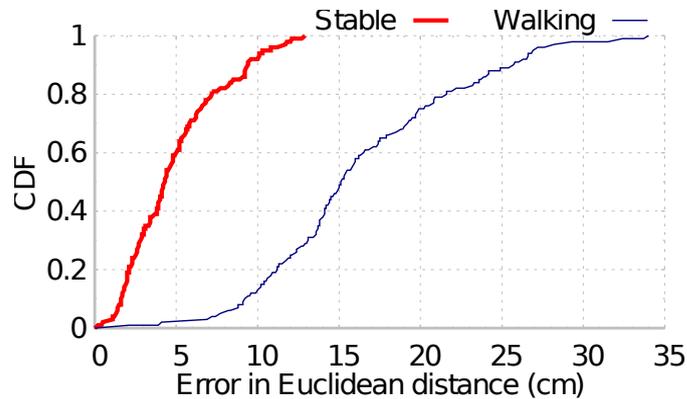
Light Identification Accuracy

Landmark Identification: **90.3%** accuracy in typical places



Localization Precision

Localization w.r.t. each light: **10cm** in ideal case, **~25cm** when walking

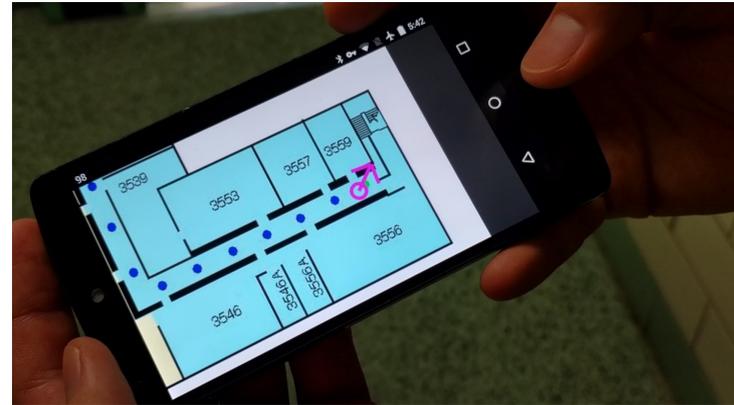


User Study

1 office building, 2 floors, 6 targets, 10 volunteers.
Find room by number.



Control Group



LiTell Group

User Study

1 office building, 2 floors, 6 targets, 10 volunteers.
Find room by number.



Control Group

Travels 50-70m less in average
(shortest path 35-132m)

Can save over 50% time

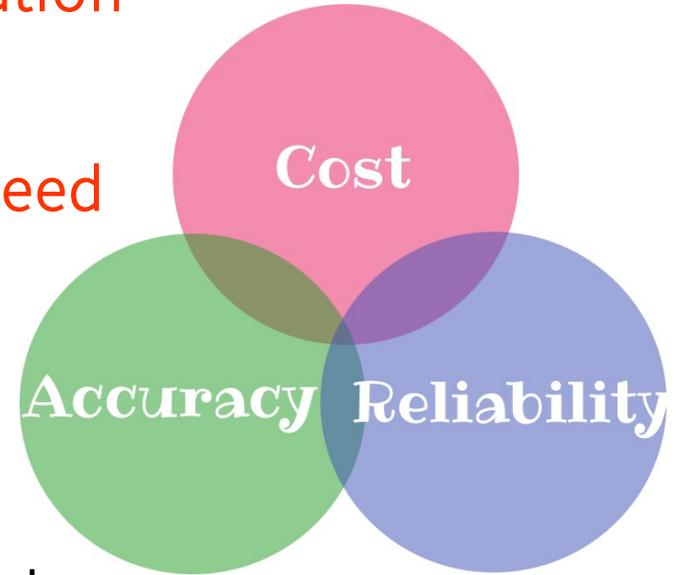
Comparable to oracle



L1ell Group

Conclusion

- LiTell uses **fluorescent lights** as **zero-cost location landmarks**
- LiTell turns **smartphone cameras** into **high speed light sensors**
- Deterministic visible light channel assures LiTell's **accuracy** and **robustness**
- LiTell brings accurate visible light localization to **today's** buildings



Thanks!

